

Communication

Buckling and Post-Buckling Behavior of the Delaminated Composite Plates

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ABSTRACT: Multilayer composite materials, having high specific strength and rigidity, are sensitive to interlayer defects. The problem of interlayer laminations in a composite plate subjected to a plane compressive load is studied using a new analytical structure previously developed by the authors. Elastic characteristics of a multilayer package of thin lamination, including the elastic characteristics of separate layers, depending on modulus of elasticity, shear modulus, Poisson's ratio, and angle of orientation of fibers of the unidirectional layer, are determined. Ratios are obtained for the unidirectional composite material that reflect the contribution of each component (fiber, matrix) in proportion to its volume fraction, according to the so-called "mixture rule". This work examines the behavior after the loss of stability of an elliptical defect in a composite plate. Only the local bulging of the delamination type defect was considered. The difference between this work and others lies in the fact that the application of the developed method, based on the energy approach, makes it possible to obtain explicit analytical expressions for quantities characterizing the critical load and describing the supercritical behavior of the detached part. The energy method is generalized to the case of analyzing the stability of defects in a non-linear formulation. The value of the critical load was obtained, and the analysis of the supercritical deformation of the defect was made.

Keywords: Stability; Composite materials; Critical load; Impact load; Stiffness characteristics; Defects; Delamination; Nonlinear deformation; Computer modeling

1. Introduction

Interest in the use of composite materials has now increased. Multilayer composite materials with high specific strength and rigidity are sensitive to interlayer defects. Delamination is the most common type of defect and is often considered a determining factor in deciding the use of composites in structures.



Delamination may occur at stress concentrations or in the area of abrupt changes in material thickness, as a result of imperfections in production technology or the action of operational loads [1,2].

The tasks of studying the plate with interlayer defects during axial compression have received a lot of attention since the 1980s, starting with the work of Chai and colleagues [3,4]. A large number of studies of this problem mainly determine the critical load [5–12].

When the critical load is reached, three types of buckling of structural elements made of composite materials with delamination defects are possible [9,13]. The first type of buckling is the global buckling of the entire plate, the buckling of the composite beam as a whole. It is observed with defects of short length. The second type of buckling is local bulging of the defect; the remaining parts of the plate remain flat. Local buckling is the main type of compression failure of laminated composites with thin lamination defects. The third type of buckling is called “mixed”, in which both local and global buckling are possible when the defect and the rest of the plate are bent.

The objectives of studying the supercritical behavior of a local interlayer defect occurring in a plate are proposed in [5,6,8,9,12]. A post-buckling study for a plate supported on all edges and containing an embedded lamination can be found in [10–12,14]. However, only Ref. [8] considers a non-rectangular, elliptical delamination shape. Information in the literature on post-buckling behavior for elliptically delaminated composite plates is rare. In addition, the problem of a composite plate with embedded lamination loaded by axial compression is mainly studied using the finite element method. Thus, analytical approaches to modeling are lacking.

This work examines the behavior after the loss of stability of an elliptical defect in a composite plate. Only the local bulging of the delamination type defect was considered. The difference between this work and others lies in the fact that the application of the developed method, based on the energy approach, makes it possible to obtain explicit analytical expressions for quantities characterizing the critical load and describing the supercritical behavior of the detached part. The energy method is generalized to the case of analyzing the stability of defects in a non-linear formulation. The value of the critical load was obtained and the analysis of the supercritical deformation of the defect was made.

2. Development and Modeling

In the cycle of strength calculations, stability calculations play an essential role, since the failure of thin-walled structural elements during compression is usually associated with a loss of general or local stability [5–10]. Consider of a delaminated composite plate subjected to in-plane compressive loading ε_x , ε_y (Figure 1). The center of the defect coincides with the origin of the oxy coordinates. We will consider the defect as a thin axisymmetric plate, pinched along the contour and subjected to a uniformly distributed load with an intensity q_x , q_y corresponding to the main load of the structural element. Forces corresponding to warp deformations are set along the defect contour ε_x , ε_y ,

$$q_x = \frac{\varepsilon_x E_x h}{1 - \mu_{xy}}; \quad q_y = \frac{\varepsilon_y E_y h}{1 - \mu_{yx}}.$$

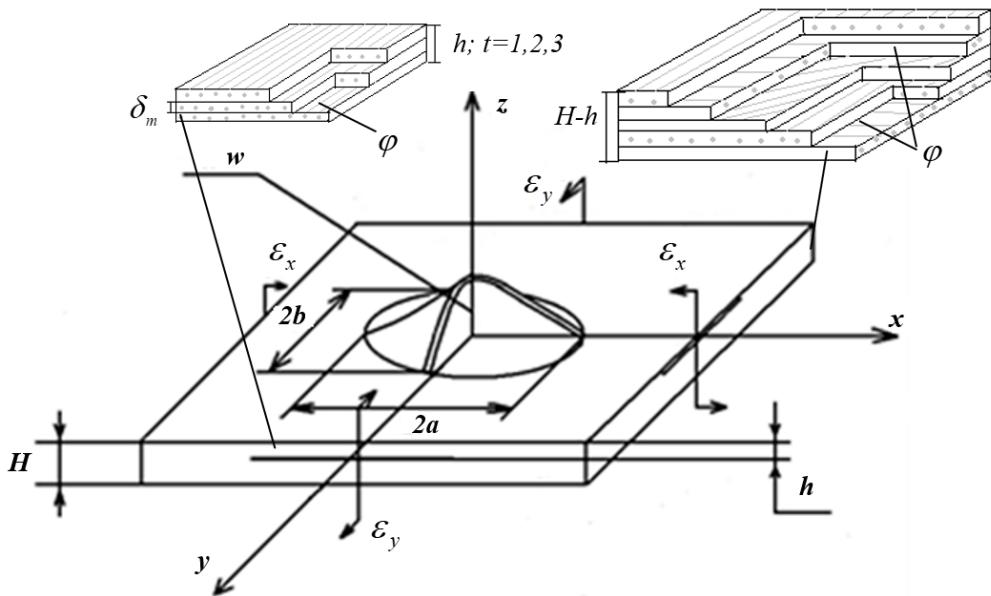


Figure 1. A composite plate with delamination, loaded with compressive deformations at the ends $\varepsilon_x, \varepsilon_y$.

For thin-walled multilayer structural elements, a plane stress state and bending are typical [6–9]. The boundaries of the local bundle are given by the equation

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1,$$

the semi-axes of the bundle are a and b , h is the thickness of the bundle. In addition, h satisfies the condition $h \ll a, b$. In the region of stratification, a multilayer plate consists of two parts (Figure 1): a stratified layer (upper part h) and a layer located below the stratification (lower part is thick $H-h$). The main part of the laminated plate with thickness H is located outside the defect. The plate consists of n layers, t —number of lamination layers, δ_m —thickness of m —one layer, m —number of layers.

The behavior of multilayer composite materials under load, even with a linear dependence of deformations on stresses, is fundamentally different from the behavior of isotropic [7,8]. To determine the elastic characteristics of a multilayer plate package and local stratification, we use the relations for unidirectional material that reflect the contribution of each component in proportion to its volume fraction, the so-called “mixture rule” [9,10]. Let’s imagine a unidirectional composite material (OKM) in the form of alternating layers with matrix and fiber properties. Then $f_e + f_M = 1$, where f_e the relative volume content of fiber in the OKM, f_M is the relative volume content of matrix in the OKM. Using a JSM-6510LV JEOL scanning electron microscope (JEOL Ltd., Tokyo, Japan), the volume fraction of fiber f_e (Figure 2) for glass fiber $d = 6 \mu\text{m}$ was determined, the fraction of which is 0.7 (percentage of fiber—70%).

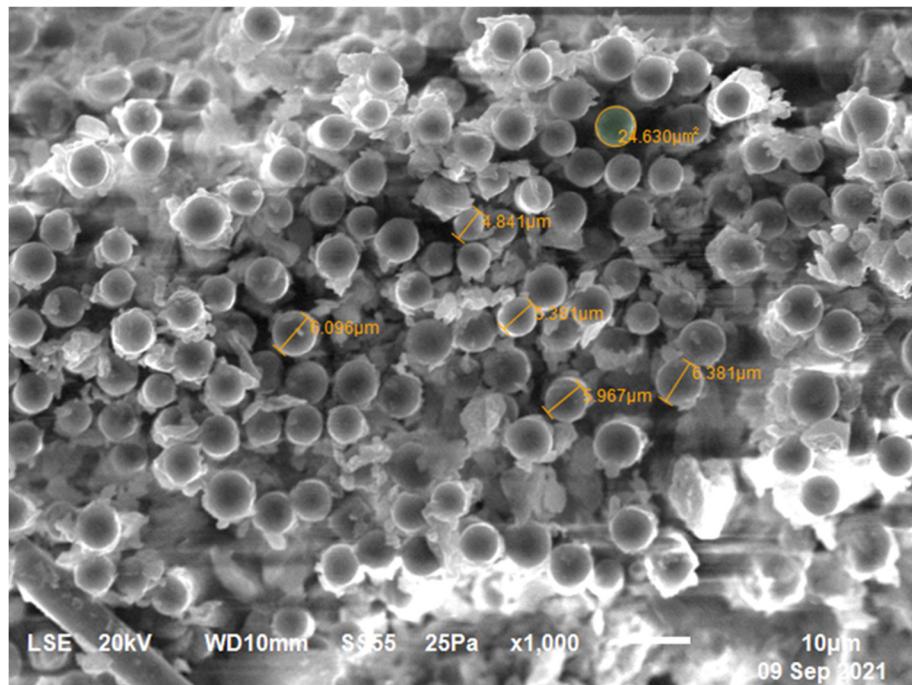


Figure 2. Cross-section image of a single fiber. Accelerating voltage: 20 kV, WD:10 mm, detector: S355, mode (25Pa) magnification 1000.

The elastic characteristics of the fiber and matrix for OCM are shown in Table 1.

Table 1. Elastic characteristics of the fiber and matrix.

Elastic Characteristics of Fiberglass	Elastic Characteristics of the Epoxy Matrix
$E_g = 7.3 \times 10^4$ MPa	$E_m = 3.78 \times 10^3$ MPa
$G_g = 2.9 \times 10^4$ MPa	$G_m = 1.4 \times 10^3$ MPa
$\mu_g = 0.22$	$\mu_m = 0.35$

We find the values of the elastic constants OKM in terms of the elastic constants and the volume fractions of the components using the following expressions:

$$\begin{aligned}
 E_1 &= f_g \mu_g + f_m \mu_m \\
 E_2 &= \frac{E_g E_m E_1}{E_1 [f_g E_m + f_m E_g] - f_g f_m (\mu_m E_g - \mu_g E_m)} \\
 G_{12} &= \frac{G_g G_m}{f_g G_m + f_m G_g} \\
 \mu_{12} &= f_g \mu_g + f_m \mu_m \\
 \mu_{21} &= \frac{\mu_{12} E_2}{E_1}
 \end{aligned} \tag{1}$$

where E_1 is the modulus of elasticity along the reinforcement direction, E_2 is the modulus of elasticity across the reinforcement direction, G_{12} is the shear modulus in the layer plane, μ_{12}, μ_{21} and are the coefficients of transverse deformations. The elastic constants for OKM, according to relations (1), are presented in Table 2. The analytical values are refined through numerical calculations in the Ansys Mechanical software package (Ansys 2024 R2).

Table 2. Elastic characteristics of OKM.

The Elastic Characteristics of OKM (Fiberglass) Are Obtained by the Ratios (1)	The Elastic Characteristics of OKM (Fiberglass) Were Obtained in the Ansys Mechanical Software Package.
$E_1 = 5.223 \times 10^4$ MPa	$E_1 = 5.225 \times 10^4$ MPa
$E_2 = 1.124 \times 10^4$ MPa	$E_2 = 1.759 \times 10^4$ MPa
$G_{12} = 4.207 \times 10^3$ MPa	$G_{12} = 4.459 \times 10^4$ MPa
$\mu_{21} = 0.259$	$\mu_{21} = 0.253$

The elastic characteristics of a multilayer package are determined if the stiffness characteristics of the individual layers included in it are known: $C_{j,s}^m$ — the stiffness characteristics of the 1st layer, depending on the elastic modulus, shear modulus, Poisson coefficients and the angle of orientation of the fibers of the unidirectional layer $E_1, E_2, G_{12}, \mu_{12}, \mu_{21}, \varphi$ (φ — the angle of orientation of the fibers of the layer). Expressions for the stiffness characteristics of the layer were obtained on the basis of [15,16]

$$\begin{aligned}
 C_{11}^m &= \lambda(E_1 \cos^4 \varphi + E_2 \sin^4 \varphi + \frac{1}{2} \mu_{12} E_2 \sin^2 2\varphi) + G_{12} \sin^2 2\varphi; \\
 C_{22}^m &= \lambda(E_1 \sin^4 \varphi + E_2 \cos^4 \varphi + \frac{1}{2} \mu_{12} E_2 \sin^2 2\varphi) + G_{12} \sin^2 2\varphi; \\
 C_{12}^m &= \lambda[(E_1 + E_2) \sin^2 \varphi \cos^2 \varphi + \mu_{12} E_2 (\cos^4 \varphi + \sin^4 \varphi)] - G_{12} \sin^2 2\varphi; \\
 C_{13}^m &= [\frac{\lambda}{2} (E_2 \sin^2 2\varphi - E_1 \cos^2 2\varphi + \mu_{12} E_2 \cos 2\varphi) + G_{12} \cos 2\varphi] \sin 2\varphi; \\
 C_{23}^m &= [\frac{\lambda}{2} (E_2 \cos^2 2\varphi - E_1 \sin^2 2\varphi - \mu_{12} E_2 \cos 2\varphi) - G_{12} \cos 2\varphi] \sin 2\varphi; \\
 C_{33}^m &= \frac{\lambda \sin^2 2\varphi}{4} (E_1 + E_2 - 2\mu_{12} E_2) + G_{12} \cos^2 2\varphi; \\
 \lambda &= \frac{1}{1 - \mu_{12} \mu_{21}}; \quad E_1 \mu_{21} = E_2 \mu_{12}.
 \end{aligned} \tag{2}$$

Let us consider the case of a local loss of stability, when the loss of stability begins with the bulging of a thin bundle. With sufficient accuracy for engineering calculations, it is possible to calculate the elastic characteristics of a multilayer composite material for layering (upper part):

$$\begin{aligned}
 A_{11} &= \frac{1}{h} \sum_{m=1}^t \delta_m C_{11}^m; \quad A_{11} = \frac{1}{h} \sum_{m=1}^t \delta_m C_{11}^m; \quad A_{22} = \frac{1}{h} \sum_{m=1}^t \delta_m C_{22}^m; \\
 E_x &= A_{11} - \frac{A_{12}^2}{A_{22}}; \quad E_y = A_{22} - \frac{A_{12}^2}{A_{11}}; \quad \mu_{xy} = \frac{A_{12}}{A_{22}}; \quad \mu_{yx} = \mu_{xy} \frac{E_y}{E_x};
 \end{aligned} \tag{3}$$

where E_x is the modulus of elasticity along the reinforcement direction for a package of multilayer composite material, thickness h ; E_y is the modulus of elasticity across the reinforcement direction for a package of multilayer composite material, thickness h ; μ_{xy}, μ_{yx} are the coefficients of transverse deformation for a package of multilayer composite material, thickness h . Table 3 shows the values of the elastic characteristics of a multilayer composite material for layering (upper part) for two [0/90], three [0/90/0], four [0/90]2 layers of fiberglass ($t = 2, 3, 4$) [17,18].

Table 3. Elastic characteristics of elastic characteristics of multilayer composite material.

Layer Reinforcement	Stiffness Characteristics of the m -Layer, MPa						
	Angle	C_{11}^m	C_{22}^m	C_{12}^m	C_{13}^m	C_{23}^m	C_{33}^m
$m = 1 \ \varphi = 0$		5.223×10^4	1.124×10^4	3.148×10^3	0	0	4.207×10^3
$m = 0 \ \varphi = 90$		1.124×10^4	5.223×10^4	3.148×10^3	3.906×10^{-12}	1.962×10^{-14}	4.207×10^3
Elastic characteristics of a two-layer bundle [0/90]							
E_x, MPa		E_y, MPa		μ_{xy}		μ_{yx}	
2.095×10^4		2.095×10^4		0.099		0.099	
Elastic characteristics of a three-layer bundle [0/90/0]							
3.817×10^4		2.465×10^4		0.126		0.082	
4.19×10^4		4.19×10^4		0.099		0.099	

The displacements that describe the plate's transition to a new deviated state from the initial equilibrium state are represented as

$$w(x, y) = \eta w_1(x, y);$$

$$u(x, y) = \eta^2 u_2(x, y);$$

$$v(x, y) = \eta^2 v_2(x, y),$$

where η is a parameter depending on the plate loading level, the displacement components u, v, w correspond to the direction of the axes x, y, z . We take the transverse deflection function $w_1(x, y)$ as

$$w_1(x, y) = \left(1 - \frac{x^2}{a^2} - \frac{y^2}{b^2}\right)$$

To determine the displacement $u_2(x, y), v_2(x, y)$ it is necessary to solve an auxiliary problem. We introduce a stress function related $\phi_2(x, y)$ to deflection $w_1(x, y)$ by the Karman equation [19],

$$\nabla^2 \nabla^2 \phi_2 = E_x h \left[\left(\frac{\partial^2 w_1}{\partial x \partial y} \right)^2 - \frac{\partial^2 w_1}{\partial x^2} \frac{\partial^2 w_1}{\partial y^2} \right].$$

The boundary conditions for take the form:

$$\begin{aligned} x = \pm \frac{a}{2}, \phi_2 = 0, \frac{\partial \phi_2}{\partial x} = 0; \\ y = \pm \frac{b}{2}, \phi_2 = 0, \frac{\partial \phi_2}{\partial y} = 0. \end{aligned}$$

Given these conditions, we will set the function $\phi_2(x, y)$ next to

$$\phi_2(x, y) = \sum_{i=0}^n \sum_{j=0}^n \theta_{ij} \left(1 - \frac{x^2}{a^2} - \frac{y^2}{b^2}\right)^2 \left(\frac{x}{a}\right)^{2i} \left(\frac{y}{b}\right)^{2j},$$

where θ_{ij} are unknown coefficients. To determine it, the Karman equation must be integrated using the Galerkin method. In this case, we obtain a system of linear equations, which we solve using the Gauss method. We use dependencies u_2, v_2 to determine

$$\frac{\partial u_2}{\partial x} = -\frac{1}{2} \left(\frac{\partial w_1}{\partial x} \right)^2 + \frac{1}{E_x h} \left(\frac{\partial^2 \phi_2}{\partial y^2} - \mu_{xy} \frac{\partial^2 \phi_2}{\partial x^2} \right);$$

$$\frac{\partial v_2}{\partial y} = -\frac{1}{2} \left(\frac{\partial w_1}{\partial y} \right)^2 + \frac{1}{E_y h} \left(\frac{\partial^2 \phi_2}{\partial x^2} - \mu_{yx} \frac{\partial^2 \phi_2}{\partial y^2} \right).$$

The approximation of the nodal points is performed using polynomial regression in the MathCAD system. The submatrix function is used to calculate the coefficients of the regression polynomial.

The change in the total potential energy $\Delta\mathcal{E}$ for thin bundles with deviation from the initial plane state is determined by the expression [16,20]

$$\Delta\mathcal{E} = \eta^2 \frac{1}{2} \int_0^a \int_0^{b\sqrt{1-\left(\frac{x}{a}\right)^2}} D \left\{ \left(\frac{d^2 w_1}{dx^2} + \frac{d^2 w_1}{dy^2} \right)^2 + \eta^2 2(1 - \mu_{xy}) \left[\left(\frac{\partial^2 w_1}{\partial x \partial y} \right)^2 - \frac{\partial^2 w_1 \partial^2 w_1}{\partial x^2 \partial y^2} \right] \right\} dy dx - \eta^2 \oint_{S_2} (u_2 q_x + v_2 q_y) dS_2$$

where S_2 is the boundary of the detachment, $D = \frac{E_x h^3}{12(1 - \mu_{xy} \mu_{yx})}$ the cylindrical stiffness of the multilayer bundle.

From the condition, $\Delta\mathcal{E} = 0$ we find the critical load (4), which, for convenience, can be represented as

$$\varepsilon_{kp} = \frac{\frac{1}{2} \int_0^a \int_0^{b\sqrt{1-\left(\frac{x}{a}\right)^2}} D \left\{ \left(\frac{\partial^2 w_1}{\partial x^2} + \frac{\partial^2 w_1}{\partial y^2} \right)^2 + 2(1 - \mu_{xy}) \left[\left(\frac{\partial^2 w_1}{\partial x \partial y} \right)^2 - \frac{\partial^4 w_1}{\partial x^2 \partial y^2} \right] \right\} dy dx}{\frac{E_x h}{1 - \mu_{xy}} \left[\oint_{S_2} u_2 dS_2 + \mu \oint_{S_2} v_2 dS_2 \right]} \quad (4)$$

When considering the non-linear behavior of the detachment, when the deflection value w becomes comparable to the height of the detachment h , the displacement of the points of the median surface u, v begins to play an important role. When the plate transitions to a new perturbed state adjacent to the initial plane, the displacement functions are taken as:

$$w(x, y) = w_0 + \eta w_1;$$

$$u(x, y) = u_0 + \eta^2 u_2$$

$$v(x, y) = v_0 + \eta^2 v_2$$

where η is a parameter that depends on the loading condition of the plate. The deflection of the plate can be set by the function.

$$w_1 = \left(1 - \frac{x^2}{a^2} - \frac{y^2}{b^2} \right)^2$$

The boundary conditions are as follows $w_1 = \frac{\partial w_1}{\partial x} = \frac{\partial w_1}{\partial y} = 0$.

The displacements of the median surface u_2 and v_2 are defined above.

The components of the deformations in the new perturbed equilibrium state can be calculated with an accuracy of η^2

$$\begin{aligned}\varepsilon_x &= \varepsilon_x^0 + \varepsilon_x''; \\ \varepsilon_y &= \varepsilon_y^0 + \varepsilon_y''; \\ \gamma_{xy}'' &= 0,\end{aligned}$$

where $\varepsilon_x^0, \varepsilon_y^0$ -components of deformations in the initial state, $\varepsilon_x'', \varepsilon_y''$ -components of deformations of the second order of smallness

$$\begin{aligned}\varepsilon_x^0 &= \frac{\partial u_0}{\partial x}; \\ \varepsilon_y^0 &= \frac{\partial v_0}{\partial y}; \\ \varepsilon_x'' &= \eta^2 \frac{\partial u_2}{\partial x} + \eta^2 \frac{1}{2} \left(\frac{\partial w_1}{\partial x} \right)^2; \\ \varepsilon_y'' &= \eta^2 \frac{\partial v_2}{\partial y} + \eta^2 \frac{1}{2} \left(\frac{\partial w_1}{\partial y} \right)^2\end{aligned}$$

The deformation energy of the median surface of the plate has the form.

$$\begin{aligned}U &= U_0 + U_2 + U_4, \\ U_0 &= \frac{E_x h}{2(1 - \mu_{xy} \mu_{yx})} \int_0^a \int_0^{b\sqrt{1-(x/a)^2}} (\varepsilon_x^{0^2} + 2\mu_{xy} \varepsilon_y^0 \varepsilon_x^0 + \varepsilon_y^{0^2}) dy dx, \\ U_1 &= \frac{E_x h}{2(1 - \mu_{xy} \mu_{yx})} \int_0^a \int_0^{b\sqrt{1-(x/a)^2}} [\varepsilon_x^0 \varepsilon_x'' + \varepsilon_y^0 \varepsilon_y'' + 2\mu_{xy} (\varepsilon_x^0 \varepsilon_y'' + \varepsilon_y^0 \varepsilon_x'')] dy dx, \\ U_4 &= \frac{E_x h}{2(1 - \mu_{xy} \mu_{yx})} \int_0^a \int_0^{b\sqrt{1-(x/a)^2}} (\varepsilon_x''^2 + \varepsilon_y''^2 + 2\mu_{xy} \varepsilon_y'' \varepsilon_x'') dy dx\end{aligned}$$

The potential of external forces is determined by the expression for the ellipse defect.

$$\Pi = \Pi_0 + \Pi_2 = \Pi_0 + \eta^2 \oint_{S_1} (u_2 q_x + v_2 q_y) ds_1,$$

The boundary of the interlayer defect is S_1 .

The displacements $u_2(x, y)$ and $v_2(x, y)$ are chosen so that all terms containing the initial conditions are excluded from the equation U_2 . Let's calculate the change in the total potential energy of the plate in the form

$$\begin{aligned}\Delta \mathcal{E} = \mathcal{E} - \mathcal{E}_0 &= \eta^2 \frac{D}{2} \int_0^a \int_0^{b\sqrt{1-(x/a)^2}} \left\{ \left(\frac{\partial^2 w_1}{\partial x^2} + \frac{\partial^2 w_1}{\partial y^2} \right)^2 + 2(1 - \mu_{xy}) \left[\left(\frac{\partial^2 w_1}{\partial x \partial y} \right)^2 - \frac{\partial^4 w_1}{\partial x^2 \partial y^2} \right] \right\} dy dx + \\ &\eta^4 \frac{E_x h}{2(1 - \mu_{xy} \mu_{yx})} \int_0^a \int_0^{b\sqrt{1-(x/a)^2}} \left\{ \left[\frac{\partial u_2}{\partial x} + \frac{1}{2} \left(\frac{\partial w_1}{\partial x} \right)^2 \right]^2 + \left[\frac{\partial v_2}{\partial y} + \frac{1}{2} \left(\frac{\partial w_1}{\partial y} \right)^2 \right]^2 + \right. \\ &\left. 2\mu_{xy} \left[\frac{\partial u_2}{\partial x} + \frac{1}{2} \left(\frac{\partial w_1}{\partial x} \right)^2 \right] \left[\frac{\partial v_2}{\partial y} + \frac{1}{2} \left(\frac{\partial w_1}{\partial y} \right)^2 \right] \right\} dy dx - \eta^2 \oint_{S_1} (u_2 q_x + v_2 q_y) ds_1.\end{aligned}$$

Equating the first derivative to zero $\frac{\partial \Delta \mathcal{E}}{\partial \eta} = 0$, we establish possible equilibrium positions

$$\eta q_{kp} + \eta^3 \frac{\frac{E_x h}{2(1-\mu_{xy}\mu_{yx})} \int_0^{a\sqrt{1-(x/a)^2}} \int_0^{b\sqrt{1-(y/b)^2}} \left\{ \left[\frac{\partial u_2}{\partial x} + \frac{1}{2} \left(\frac{\partial w_1}{\partial x} \right)^2 \right]^2 + \left[\frac{\partial v_2}{\partial y} + \frac{1}{2} \left(\frac{\partial w_1}{\partial y} \right)^2 \right]^2 + \oint_{S_1} (u_2 + \mu v_2) ds_1 \right\} dy dx - \eta q = 0}{(5)}$$

The equations for the load have the form $q_x = q = \frac{E_x h \varepsilon}{1-\mu_{xy}}$; $q_y = \mu_{yx} q = \frac{\mu_{yx} E_y h \varepsilon}{1-\mu_{xy}}$; $q_{kp} = \frac{E_x h \varepsilon_{kp}}{1-\mu_{xy}}$.

If $q < q_{kp}$, only one rectilinear form of equilibrium is possible, which corresponds to $\eta = 0$. If $q > q_{kp}$ a bending form of equilibrium is possible (5). The study of the sign of the second derivative $\frac{\partial^2 \Delta \mathcal{E}}{\partial \eta^2}$ made it possible to establish that the plane $q > q_{kp}$ form of the equilibrium is unstable, while the bending one is stable (Figure 3). The relationship between the deflection in the center of the elliptical detachment and the load is obtained in the form

$$\bar{w}_{\max} = 1.01 \sqrt{\bar{q} - 1}; \bar{q} = \frac{q}{q_{kp}}.$$

Since the exfoliated layer is quite thin, the critical load is small, and the area of subcritical deformation is large enough, it is necessary to assess the ranges of existence of the basic form of equilibrium and more complex ones. First, after the loss of stability, the deflection in the center of the defect becomes maximum [17,18]. This is the basic form of equilibrium. As loads increase, a transition to more complex forms is possible.

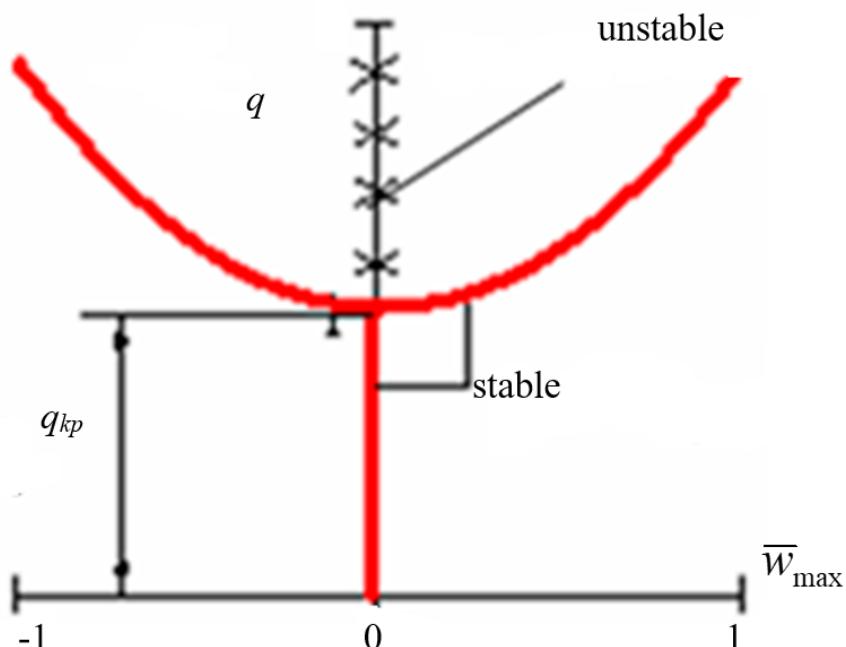


Figure 3. Flat form of equilibrium lamination is unstable, and bending form of lamination is stable.

3. Numerical Simulation

When loaded, first, after a loss of stability, the deflection at the center reaches a maximum, corresponding to the main form of equilibrium; then, under heavy loads, a transition to more complex forms is possible. To obtain numerical results, we take data corresponding to the basic form of equilibrium with the subsequent growth of the deflection boom, since this case is more dangerous from the point of view of the growth of the defect. Figure 4 shows the relationship between deflection in the center of the elliptical lamination and the load at different occurrences of the defect $\bar{h} = 0.1; 0.08; 0.06$.

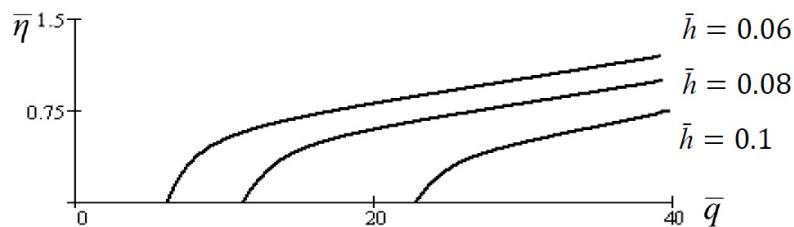


Figure 4. The relationship between deflection in the center of the elliptical lamination and the load at different occurrences of the defect $\bar{h} = 0.1; 0.08; 0.06$.

In the work, ANSYS medium [20,21] was used to calculate samples from prepreg (glass fiber), industrial grade of glass fabric—T-25 (VM) TU 6-11-380-76. Unidirectional material has the following characteristics: fiberglass— $E_1 = 5.4 \times 10^4$ MPa, $E_2 = 1.2 \times 10^4$ MPa, $G_{12} = 0.5 \times 10^4$ MPa, $\mu = 0.28$. Figures 5 and 6 show the results of the analysis of the non-linear behavior of elliptical delaminations for the case $h = 0.5$ mm; $H = 3$ mm; $a = 15$ mm; $b = 7$ mm; $L = 100$ mm. The elastic characteristics $E_x, E_y, G_{xy}, \mu_{xy}, \mu_{yx}$ of the detached plate are obtained by Equations (1)–(3). The plate consists of 24 layers: the fibers of the exfoliated layer are located in the direction of loading at an angle of 0° (Figure 5); fibers of the peeled layer are located in the direction of loading at an angle of 90° (Figure 6). Arrangement of fibers in direction of loading reduces resistance to deformation (Figure 5), arrangement of fibers in direction perpendicular to loading increases resistance to deformation (Figure 6).

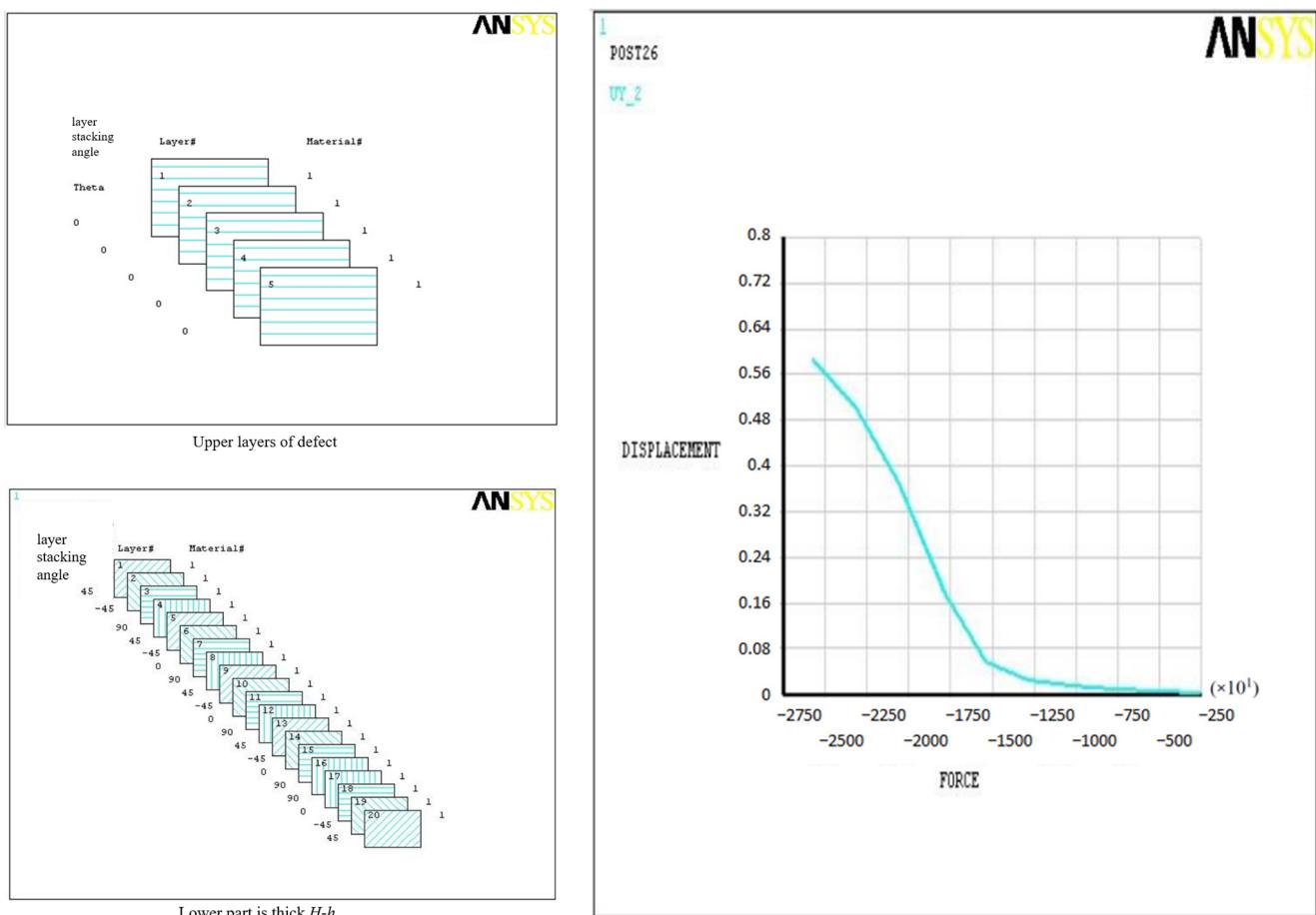


Figure 5. Force-strain dependence for laminated part of plate. The fibers of the exfoliated layer are located in the direction of loading at an angle of 0° .

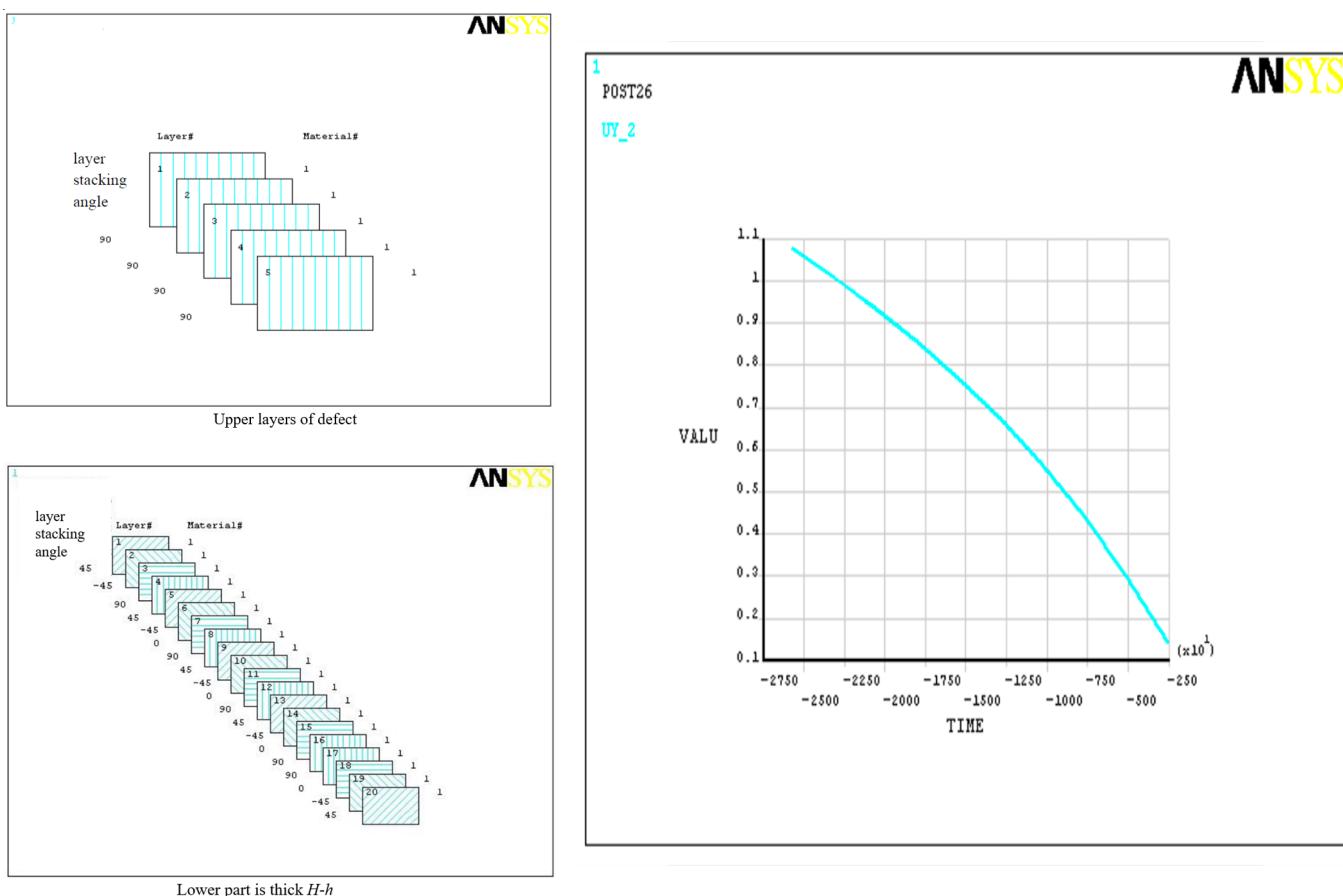


Figure 6. Force-strain dependence for laminated part of plate. The fibers of the exfoliated layer are located in the direction of loading at an angle of 90°.

4. Analysis of the Results of the Calculation

The task of studying the stability of thin-walled laminations of composite materials is considered in a non-linear formulation. A refined approach for solving this class of problems is presented. The problem of stability study in the two-dimensional case is considered using the example of elliptic delaminations in a non-linear formulation. The use of the developed method based on the energy approach allows obtaining explicit analytical expressions for the quantities characterizing the critical load and describing the supercritical behavior of the detached part. The energy method is generalized to the case of analyzing the stability of defects in a non-linear formulation. The value of the critical load was obtained, and the analysis of the supercritical deformation of the defect was made. Forms of equilibrium near the critical point of bifurcation have been investigated. Elastic characteristics of a multilayer package of thin lamination, including the elastic characteristics of separate layers included in it, depending on modulus of elasticity, shear modulus, Poisson's ratio, and angle of orientation of fibers of unidirectional layer, are determined. Ratios are obtained for the unidirectional composite material, which reflect the contribution of each component (fiber, matrix) in proportion to its volume fraction, the so-called "mixture rule". The results of the analytical solution are comparable to the numerical data. The strength estimation and numerical calculation methods discussed can also be applied to a wide range of composite materials.

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Author Contributions

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Additional data can be provided upon request.

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